

# **Data sheet for SINAMICS G120C**

Article No.: 6SL3210-1KE14-3AB2

Client order no. : Order no. : Offer no. : Remarks :





Figure simila

Rate	ed data		
nput			
Number of phases	3 AC		
Line voltage	380 480 V +1	0 % -20 %	
Line frequency	47 63 Hz		
Rated current (LO)	5.50 A		
Rated current (HO)	4.50 A		F
Output			
Number of phases	3 AC		D
Rated voltage	400V IEC	480V NEC 1)	
Rated power (LO)	1.50 kW	2.00 hp	
Rated power (HO)	1.10 kW	1.50 hp	
Rated current (LO)	4.10 A		
Rated current (HO)	3.10 A		Α
Rated current (IN)	4.30 A		
Max. output current	6.20 A		
Pulse frequency	4 kHz		S
Output frequency for vector control	0 240 Hz		
Output frequency for V/f control	0 550 Hz		

## Overload capability

Low Overload (LO)

 $150\,\%$  base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200~% base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor $\cos\phi$	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	49 dB	
Power loss	61.9 W	
Filter class (integrated)	Class A	
Communication		

Communication	USS/MODBUS RTU

Inputs / outputs	
Standard digital inputs	
Number	6
Switching level: 0→1	11 V
Switching level: 1→0	5 V
Max. inrush current	15 mA
Fail-safe digital inputs	
Number	1
Digital outputs	
Number as relay changeover contact	1
Output (resistive load)	DC 30 V, 0.5 A
Number as transistor	1
Output (resistive load)	DC 30 V, 0.5 A
Analog / digital inputs	
Number	1 (Differential input)
Resolution	10 bit
Switching threshold as digital input	
0→1	4 V
1→0	1.6 V
Analog outputs	
Number	1 (Non-isolated output)

#### PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy  $\pm 5\,^{\circ}\text{C}$ 

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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Ambient conditions	
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.005 m³/s (0.177 ft³/s)
Installation altitude	1,000 m (3,280.84 ft)
Ambient temperature	
Operation	-10 40 °C (14 104 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-40 70 °C (-40 158 °F)
Relative humidity	
Max. operation	$95~\%$ At $40~^\circ\text{C}$ (104 $^\circ\text{F}),$ condensation and icing not permissible
(	Connections
Signal cable	
Conductor cross-section	0.15 1.50 mm <sup>2</sup> (AWG 24 AWG 16)
Line side	
Version	Plug-in screw terminals
Conductor cross-section	1.00 2.50 mm <sup>2</sup> (AWG 18 AWG 14)
Motor end	
Version	Plug-in screw terminals
Conductor cross-section	1.00 2.50 mm <sup>2</sup> (AWG 18 AWG 14)

DC	link	(for	braking	resistor)
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Version	Plug-in screw terminals
Conductor cross-section	1.00 2.50 mm <sup>2</sup> (AWG 18 AWG 14)
Line length, max.	15 m (49.21 ft)
PE connection	On housing with M4 screw

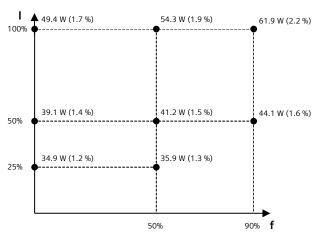
### Max. motor cable length

Shielded	50 m (164.04 ft)
Unshielded	100 m (328.08 ft)

Mechanical data		
Degree of protection	IP20 / UL open type	
Frame size	FSAA	
Net weight	1.40 kg (3.09 lb)	
Dimensions		
Width	73 mm (2.87 in)	
Height	173 mm (6.81 in)	
Depth	155 mm (6.10 in)	

Standards	
Compliance with standards	UL, cUL, CE, C-Tick (RCM)
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC

Converter losses to IEC61800-9-2*	
Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	30.3 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

<sup>\*</sup>converted values

 $<sup>^{1)}</sup>$ The output current and HP ratings are valid for the voltage range 440V-480V