## SIEMENS



SIMATIC S7-300, FM352-5 with PNP output, High Speed Boolean Processor, for high-speed linking, 12 DI, 8 DO, 1 encoder interface for RS422 incr./SSI encoder

Figure similar

| Supply voltage |  |
| :---: | :---: |
| Load voltage L+ |  |
| - Rated value (DC) <br> - permissible range, lower limit (DC) <br> - permissible range, upper limit (DC) <br> - Reverse polarity protection | $\begin{aligned} & 24 \mathrm{~V} \\ & 20.4 \mathrm{~V} \\ & 28.8 \mathrm{~V} \\ & \text { Yes } \end{aligned}$ |
| Input current |  |
| from load voltage1L+, max. | 150 mA ; typ. 60 mA |
| from load voltage 2L+ (without load), max. | 200 mA ; typ. 60 mA , DI/DO supply |
| from load voltage 3L+ (with encoder), max. | 600 mA ; typ. 80 mA plus encoder supply |
| from load voltage 3L+ (without load), max. | 200 mA ; typ. 80 mA |
| from backplane bus 5 V DC, typ. | 135 mA |
| Encoder supply |  |
| 5 V encoder supply |  |
| - 5 V <br> - Short-circuit protection <br> - Output current, max. | Yes <br> Yes; Electronic overload protection; no protection on applying a normal or counter voltage. $250 \mathrm{~mA}$ |
| 24 V encoder supply |  |
| - 24 V <br> - Short-circuit protection <br> - Output current, max. | Yes <br> Yes; Overvoltage and overheating protection if overloaded; diagnostics if output reaches temperature limit; no protection on applying a normal or counter voltage $400 \mathrm{~mA}$ |
| Power loss |  |
| Power loss, typ. | 6.5 W |
| Memory |  |
| Type of memory | RAM |
| Memory size | 128 kbyte; required for operation, MMC |
| Digital inputs |  |
| Number of digital inputs | 8; Standard and up to 12 with 24 V DC encoder inputs as digital inputs |
| Input voltage |  |
| - Rated value (DC) <br> - for signal "0" <br> - for signal "1" | $\begin{aligned} & 24 \mathrm{~V} \\ & -30 \text { to }+5 \mathrm{~V} \\ & +11 \text { to }+30 \mathrm{~V} \end{aligned}$ |
| Input current |  |
| - for signal "0", max. (permissible quiescent current) <br> - for signal "1", typ. | 1.5 mA 3.8 mA |

[^0]- Input frequency (with a time delay of 0.1 ms ), max.
- programmable digital filter delay
- Minimum pulse width for program reactions for standard inputs
— at "0" to "1", max.

Cable length

- shielded, max.
- unshielded, max.


## 200 kHz

None, $5 \mu \mathrm{~s}, 10 \mu \mathrm{~s}, 15 \mu \mathrm{~s}, 20 \mu \mathrm{~s}, 50 \mu \mathrm{~s}, 1.6 \mathrm{~ms}$
$1 \mu \mathrm{~s}, 5 \mu \mathrm{~s}, 10 \mu \mathrm{~s}, 15 \mu \mathrm{~s}, 20 \mu \mathrm{~s}, 50 \mu \mathrm{~s}, 1,6 \mathrm{~ms}$
$3 \mu \mathrm{~s}$; typ. $1.5 \mu \mathrm{~s}$

600 m
100 m ; Shielded cable recommended if filtering delay is set to less than 1.6 ms

## Digital outputs

Number of digital outputs 8

Current-sinking No
Current-sourcing
Short-circuit protection

- Response threshold, typ.

Limitation of inductive shutdown voltage to

## Controlling a digital input

Switching capacity of the outputs

- on lamp load, max.

5 W
Output voltage

- Rated value (DC)
- for signal "0", max.
- for signal "1", max.

24 V
28.8 V
0.5 V

Output current

- for signal "1" rated value
- for signal "1" permissible range for 0 to $60^{\circ} \mathrm{C}$, min.
- for signal " 1 " permissible range for 0 to $60^{\circ} \mathrm{C}$, max.
- for signal " 0 " residual current, max.


## $0.5 \mathrm{~A} ;$ At $60^{\circ} \mathrm{C}$

5 mA
600 mA
1 mA
Output delay with resistive load

- "0" to "1", max.
$1 \mu \mathrm{~s} ; 0.6 \mu \mathrm{~s} 50 \mathrm{~mA} / 1.0 \mu \mathrm{~s} 0.5 \mathrm{~A}$
- "1" to "0", max.
$1.5 \mu \mathrm{~s} ; 1.7 \mu \mathrm{~s} 50 \mathrm{~mA} / 1.5 \mu \mathrm{~s} 0.5 \mathrm{~A}$
Parallel switching of two outputs
- for uprating

Yes; 2
Switching frequency

- with resistive load, max.
- with inductive load, max.
- on lamp load, max.
$2 \mathrm{~Hz} ; 2 \mathrm{~Hz}$ at 0.5 A with external commutator diodes; 0.5 Hz at 0.5 A without external commutator diodes

10 Hz
Cable length

- shielded, max. 600 m
- unshielded, max.

100 m

## Encoder

Connectable encoders

- Incremental encoder (symmetrical)


## Yes

- Incremental encoder (asymmetrical)
- Absolute encoder (SSI)
- 2-wire sensor
- permissible quiescent current (2-wire sensor), max.
Encoder signals, incremental encoder (symmetrical)
- Trace mark signals
$A, \operatorname{not} A, B, \operatorname{not} B$
$\mathrm{N}, \operatorname{not} \mathrm{N}$
5 V difference signal (phys. RS 422)
500 kHz
100 m ; 100 m with 24 V supply and $500 \mathrm{kHz} ; 32 \mathrm{~m}$ with 5 V supply and 500 kHz

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A,B
N
24 V
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- Input frequency, max.
- Cable length, shielded, max

| Encoder signals, absolute encoder (SSI) |  |
| :---: | :---: |
| - Data signal <br> - Clock signal <br> - Telegram length, parameterizable <br> - Clock frequency, max. <br> - Cable length, shielded, max. <br> - Monoflop time <br> - Listening mode <br> - Multiturn | DATA, notDATA <br> CK, notCK <br> 13 or 25 bit <br> $1 \mathrm{MHz} ; 125 \mathrm{kHz}, 250 \mathrm{kHz}, 500 \mathrm{kHz}$ or 1 MHz <br> 320 m ; At 125 kHz <br> settable: 16/32/48/64 $\mu \mathrm{s}$ <br> Yes; one or two stations <br> Yes; 25 bit message frame |
| Encoder signal evaluation |  |
| - Counting direction, forward <br> - Counting direction, backward | Yes <br> Yes |
| Response times |  |
| Input- to output response time | 5 V input to 24 V output, 0 filter: 1 to $4 \mu \mathrm{~s}$ (typ.); 24 V input to 24 V output, 0 filter: 2 to $6 \mu \mathrm{~s}$ (typ.) |
| Interfaces |  |
| Point-to-point connection |  |
| - Updating times | PLC interface: 1.7 ms |
| Interrupts/diagnostics/status information |  |
| Alarms |  |
| - Diagnostic alarm | Yes; 1L, 2L, 3L missing; MMC error; output overload (8); encoder supply overload; differential wire break; parameterization errror; SSI message frame overflow |
| - Hardware interrupt | Yes; 8 available; for generation by user program |
| Diagnoses |  |
| - Wire-break in signal transmitter cable <br> - Overflow/underflow <br> - missing load voltage | Yes <br> Yes <br> Yes |
| Diagnostics indication LED |  |
| - RUN/STOP LED <br> - Module supply 5 V DC (green) <br> - I/O status IOF (red) <br> - Micro Memory Card error MCF (red) <br> - Group error SF (red) <br> - Status indicator digital input (green) <br> - Status indicator digital output (green) <br> - Overload encoder supply voltage 24 V F (red) <br> - Overload encoder supply voltage 5 V F (red) | Yes <br> Yes <br> Yes <br> Yes <br> Yes <br> Yes; I 0 tol 11 <br> Yes; Q 0 to Q 7 <br> Yes <br> Yes |
| Counter |  |
| Counting range, description | Counting range (16-bit counters): -32768 to 32767 (user-specific within this range); counting range (32-bit counters): -2 147483648 to 2147 483647 (user-specific within this range) |
| Counting range, lower limit | -2 147483648 |
| Counting range, upper limit | 2147483647 |
| Counting mode |  |
| - Counting mode, individual <br> - Counting mode, continuous <br> - Counting mode, periodic | Yes <br> Yes <br> Yes |
| Potential separation |  |
| between 1L and 2L and 3L | Yes |
| Potential separation digital inputs |  |
| - Potential separation digital inputs | Yes; Yes CPU, I/O and sensor units are isolated |
| Ambient conditions |  |
| Ambient temperature during operation |  |
| - min. <br> - max. | $\begin{aligned} & 0^{\circ} \mathrm{C} \\ & 60^{\circ} \mathrm{C} \end{aligned}$ |

$\bullet$ min. $-40^{\circ} \mathrm{C}$

- max.
$\frac{\text { configuration / header }}{\text { configuration / programming / header }}$
- Program cycle time (scan) $1 \mu \mathrm{~s}$

| connection method / header | 1x 40-pin |
| :--- | :--- |
| required front connector | 80 mm |
| Dimensions | 125 mm |
| Width | 120 mm |
| Height |  |
| Depth | $434 \mathrm{~g} ;$ Module weight: approx. 434 g (with 1 L connection and without |
| Weights | I/O connection or MMC); shipping weight: approx. 500 g (with bus and |
| Weight, approx. | 1 L connection and without I/O connection or MMC) |

## last modified:


[^0]:    Input delay (for rated value of input voltage)

