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Data sheet for SINAMICS G120C

Article No. :

6SL3210-1KE23-2AP1



Figure similar

Client order no.	:
Order no. :	
Offer no. :	
Remarks :	

Rate	Rated data		
Input			
Number of phases	3 AC		
Line voltage	380 480 V +10 %	6 -20 %	
Line frequency	47 63 Hz		
Rated current (LO)	40.60 A		
Rated current (HO)	36.40 A		
Output			
Number of phases	3 AC		
Rated voltage	400V IEC	480V NEC ¹⁾	
Rated power (LO)	15.00 kW	20.00 hp	
Rated power (HO)	11.00 kW	15.00 hp	
Rated current (LO)	31.00 A		
Rated current (HO)	25.00 A		
Rated current (IN)	32.00 A		
Max. output current	50.00 A		
Pulse frequency	4 kHz		
Output frequency for vector control	0 240 Hz		
Output frequency for V/f control	0 550 Hz		

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor $\cos \phi$	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	66 dB	
Power loss	371.0 W	
Filter class (integrated)	Class A	
Communication		

Communication

PROFIBUS DP

ltem no. : Consignment no. : Project :

Inputs / outputs			
Standard digital inputs			
Number	6		
Switching level: $0 \rightarrow 1$	11 V		
Switching level: $1 \rightarrow 0$	5 V		
Max. inrush current	15 mA		
Fail-safe digital inputs			
Number	1		
Digital outputs			
Number as relay changeover contact	1		
Output (resistive load)	DC 30 V, 0.5 A		
Number as transistor	1		
Output (resistive load)	DC 30 V, 0.5 A		
Analog / digital inputs			
Number	1 (Differential input)		
Resolution	10 bit		
Switching threshold as digital input			
0→1	4 V		
1→0	1.6 V		
Analog outputs			
Number	1 (Non-isolated output)		
PTC/ KTY interface			
1 motor temperature sensor input, sen Thermo-Click, accuracy $\pm 5~^\circ\mathrm{C}$	sors that can be connected PTC, KTY and		
Closed-loop control techniques			
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		

Yes

No

No

No

	•		

Sensorless vector control

Vector control, with sensor

Encoderless torque control

Torque control, with encoder

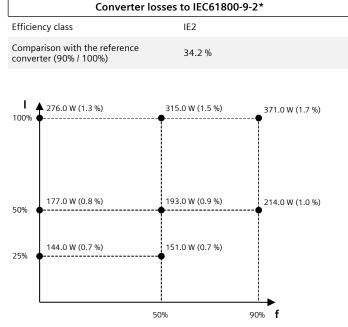
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Ambient conditions			
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.018 m³/s (0.636 ft³/s)		
Installation altitude 1,000 m (3,280.84 ft)			
Ambient temperature			
Operation	-10 40 °C (14 104 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-40 70 °C (-40 158 °F)		
Relative humidity			
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible		
Co	onnections		
Signal cable			
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Line side			
Version	Plug-in screw terminals		
Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)		
Motor end			
Version	Plug-in screw terminals		
Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)		
DC link (for braking resistor)			
Version	Plug-in screw terminals		
Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)		
Line length, max.	15 m (49.21 ft)		
PE connection	On housing with M4 screw		
Max. motor cable length			
Shielded	50 m (164.04 ft)		
Unshielded	150 m (492.13 ft)		
Мес	hanical data		
Degree of protection	IP20 / UL open type		
Frame size	FSC		
Net weight	4.40 kg (9.70 lb)		
Dimensions			
Width	140 mm (5.51 in)		
Height	295 mm (11.61 in)		
Depth	203 mm (7.99 in)		
Standards			
Compliance with standards	UL, cUL, CE, C-Tick (RCM)		
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC		



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values

 $^{1)}\mbox{The}$ output current and HP ratings are valid for the voltage range 440V-480V