6ES7511-1CK01-0AB0

Data sheet



SIMATIC S7-1500 Compact CPU CPU 1511C-1PN, central processing unit with working memory 175 KB for program and 1 MB for data, 16 digital inputs, 16 digital outputs, 5 analog inputs, 2 analog outputs, 6 high speed counters, 4 high speed outputs for PTO/PWM/frequency output 1. interface: PROFINET IRT with 2 port switch, 60 NS bit-performance, incl. front connector push-in, SIMATIC memory card necessary

General information	
Product type designation	CPU 1511C-1 PN
HW functional status	FS03
Firmware version	V2.9
Product function	
• I&M data	Yes; I&M0 to I&M3
 Isochronous mode 	Yes; With minimum OB 6x cycle of 625 µs (distributed)
Engineering with	
 STEP 7 TIA Portal configurable/integrated from version 	V17 (FW V2.9) / V15 (FW V2.5) or higher; with older TIA Portal versions configurable as 6ES7511-1CK00-0AB0
Configuration control	
via dataset	Yes
Display	
Screen diagonal [cm]	3.45 cm
Control elements	
Number of keys	8
Mode buttons	2
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V; 20.4 V DC, for supplying the digital inputs/outputs
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
 Mains/voltage failure stored energy time 	5 ms; Refers to the power supply on the CPU section
 Repeat rate, min. 	1/s
Input current	
Current consumption (rated value)	0.8 A; Without load; 9.8 A: CPU + load
Current consumption, max.	1 A; Without load; 10 A: CPU + load
Inrush current, max.	1.9 A; Rated value
l²t	0.34 A²·s
Digital inputs	
 from load voltage L+ (without load), max. 	20 mA; per group
Digital outputs	
 from load voltage L+, max. 	30 mA; Per group, without load
output voltage / header	
Rated value (DC)	24 V
Encoder supply	
Number of outputs	1; One common 24 V encoder supply
24 V encoder supply	

• 24 V	Yes; L+ (-0.8 V)
	Yes
Short-circuit protectionOutput current, max.	1 A
Power	17
Infeed power to the backplane bus	10 W
Power consumption from the backplane bus (balanced)	8.5 W
Power loss	0.0 17
Power loss, typ.	11.8 W
Memory	11.0 VV
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	165
• integrated (for program)	175 kbyte
• integrated (for data)	1 Mbyte
Load memory	1 Milyto
Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	60 ns
for word operations, typ.	72 ns
for fixed point arithmetic, typ.	96 ns
for floating point arithmetic, typ.	384 ns
CPU-blocks	
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	1000, 51001.0 (05, 15, 10, 55) and 05 10
Number range	1 60 999; subdivided into: number range that can be used by the
· ·	user: 1 59 999, and number range of DBs created via SFC 86: 60 000
-	60 999
• Size, max.	1 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	
	0 65 525
Number range	0 65 535
Number rangeSize, max.	0 65 535 175 kbyte
Number rangeSize, max.	175 kbyte
Number rangeSize, max.FCNumber range	175 kbyte 0 65 535
Number rangeSize, max.	175 kbyte
 Number range Size, max. FC Number range Size, max. 	175 kbyte 0 65 535 175 kbyte
 Number range Size, max. FC Number range Size, max. OB Size, max. 	175 kbyte 0 65 535
 Number range Size, max. FC Number range Size, max. OB	175 kbyte 0 65 535 175 kbyte 175 kbyte
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50 3
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50 3 1
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of technology synchronous alarm OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50 3 1
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of technology synchronous alarm OBs Number of startup OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50 3 1 2 100
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of technology synchronous alarm OBs Number of startup OBs Number of asynchronous error OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50 3 1 2 100 4
 Number range Size, max. FC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of synchronous error OBs Number of synchronous error OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50 3 1 2 100 4 2
 Number range Size, max. FC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of startup OBs Number of startup OBs Number of synchronous error OBs Number of diagnostic alarm OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50 3 1 2 100 4 2
 Number range Size, max. FC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of startup OBs Number of synchronous error OBs Number of synchronous error OBs Number of diagnostic alarm OBs 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50 3 1 2 100 4 2 1
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of asynchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50 3 1 2 100 4 2 1
 Number range Size, max. FC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of process alarm OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of asynchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs 50 3 1 2 100 4 2 1
 Number range Size, max. FC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of synchronous error OBs Number of asynchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity S7 counter 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2 1
 Number range Size, max. FC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of asynchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity S7 counter Number 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2 1
 Number range Size, max. FC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of asynchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity S7 counter Number 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2 1 24
 Number range Size, max. FC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of asynchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity S7 counter Number Retentivity — adjustable 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2 1 24
 Number range Size, max. PC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of technology synchronous alarm OBs Number of startup OBs Number of asynchronous error OBs Number of diagnostic alarm OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity S7 counter Number Retentivity adjustable IEC counter IEC counter 	175 kbyte 0 65 535 175 kbyte 175 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2 100 4 2 100 4 2 1

— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	128 kbyte; In total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 88 KB
Extended retentive data area (incl. timers, counters, flags), max.	1 Mbyte; When using PS 6 0W 24/48/60 V DC HF
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	o, o clock memory bit, grouped into one clock memory byte
Retentivity adjustable	Yes
	No
Retentivity preset Local data	IVO
	64 khyta: may 16 KP par block
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	1 024; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
Number of subprocess images, max.	32
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration
Number of distributed to systems	of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
Via CM	4; A maximum of 4 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
integrated	1
• Via CM	4; A maximum of 4 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Rack	
 Modules per rack, max. 	32; CPU + 31 modules
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	

a proported	Vee
• supported	Yes
• in AS, master	Yes
• in AS, slave	Yes
on Ethernet via NTP	Yes
Digital inputs	
integrated channels (DI)	16
Digital inputs, parameterizable	Yes
Source/sink input	P-reading
Input characteristic curve in accordance with IEC 61131, type 3	Yes
Digital input functions, parameterizable	
Gate start/stop	Yes
Capture	Yes
Synchronization	Yes
Input voltage	
Type of input voltage	DC
Rated value (DC)	24 V
• for signal "0"	-3 to +5V
• for signal "1"	+11 to +30V
Input current	
• for signal "1", typ.	2.5 mA
Input delay (for rated value of input voltage)	
for standard inputs	
— parameterizable	Yes; none / 0.05 / 0.1 / 0.4 / 1.6 / 3.2 / 12.8 / 20 ms
— at "0" to "1", min.	4 μs; for parameterization "none"
— at "0" to "1", max.	20 ms
— at "1" to "0", min.	4 μs; for parameterization "none"
— at "1" to "0", max.	20 ms
for interrupt inputs	
parameterizable	Yes; Same as for standard inputs
for technological functions	
— parameterizable	Yes; Same as for standard inputs
Cable length	
shielded, max.	1 000 m; 600 m for technological functions; depending on input
	frequency, encoder and cable quality; max. 50 m at 100 kHz
• unshielded, max.	600 m; for technological functions: No
Digital outputs	
Type of digital output	Transistor
integrated channels (DO)	16
Current-sourcing	Yes; Push-pull output
Short-circuit protection	Yes; electronic/thermal
 Response threshold, typ. 	1.6 A with standard output, 0.5 A with high-speed output; see manual for details
Limitation of inductive shutdown voltage to	-0.8 V
Controlling a digital input	Yes
Accuracy of pulse duration	Up to ±100 ppm ±2 μs at high-speed output; see manual for details
minimum pulse duration	2 μs; With High Speed output
Digital output functions, parameterizable	,
Switching tripped by comparison values	Yes; As output signal of a high-speed counter
PWM output	Yes
— Number, max.	4
Cycle duration, parameterizable	Yes
— ON period, min.	0 %
— ON period, max.	100 %
Resolution of the duty cycle	0.0036 %; For S7 analog format, min. 40 ns
Frequency output	Yes
Switching capacity of the outputs	
with resistive load, max.	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed
	output; see manual for details
● on lamp load, max.	5 W; 1 W with high-speed output, i.e. when using a high-speed output;
	see manual for details

Load resistance range	
• lower limit	48 $\Omega;$ 240 ohms with high-speed output, i.e. when using a high-speed output; see manual for details
upper limit	12 kΩ
Output voltage	
 Type of output voltage 	DC
• for signal "0", max.	1 V; With high-speed output, i.e. when using a high-speed output; see manual for details
● for signal "1", min.	23.2 V; L+ (-0.8 V)
Output current	
• for signal "1" rated value	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed output, observe derating; see manual for details
for signal "1" permissible range, min.	2 mA
for signal "1" permissible range, max.	0.6 A; 0.12 A with high-speed output, i.e. when using a high-speed output, observe derating; see manual for details
for signal "0" residual current, max.	0.5 mA
Output delay with resistive load	
• "0" to "1", max.	200 μs
• "1" to "0", max.	500 μs; Load-dependent
for technological functions	
— "0" to "1", max.	$5\ \mu s;$ Depending on the output used, see additional description in manual
— "1" to "0", max.	5 μs; Depending on the output used, see additional description in manual
Parallel switching of two outputs	
 for logic links 	Yes; for technological functions: No
for uprating	No
for redundant control of a load	Yes; for technological functions: No
Switching frequency	
 with resistive load, max. 	100 kHz; For high-speed output, 100 Hz for standard output
 with inductive load, max. 	0.5 Hz; Acc. to IEC 60947-5-1, DC-13; observe derating curve
 on lamp load, max. 	10 Hz
Total current of the outputs	
 Current per channel, max. 	0.5 A; see additional description in the manual
 Current per group, max. 	8 A; see additional description in the manual
Current per power supply, max.	4 A; 2 power supplies for each group, current per power supply max. 4 A, see additional description in manual
for technological functions	
 Current per channel, max. 	0.5 A; see additional description in the manual
Relay outputs	
 Number of relay outputs 	0
Cable length	
• shielded, max.	1 000 m; 600 m for technological functions; depending on output frequency, load, and cable quality; max. 50 m at 100 kHz
unshielded, max.	600 m; for technological functions: No
nalog inputs	
Number of analog inputs	5; 4x for U/I, 1x for R/RTD
For current measurement	4; max.
For voltage measurement	4; max.
For resistance/resistance thermometer measurement	1
permissible input voltage for voltage input (destruction limit), max.	28.8 V
permissible input current for current input (destruction limit), max.	40 mA
Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency suppression; for details, see conversion procedure in manual
Technical unit for temperature measurement adjustable	Yes; °C/°F/K
Input ranges (rated values), voltages	
• 0 to +10 V	Yes; Physical measuring range: ± 10 V
— Input resistance (0 to 10 V)	100 kΩ
• 1 V to 5 V	Yes; Physical measuring range: ± 10 V
— Input resistance (1 V to 5 V)	100 kΩ

• -10 V to +10 V	Voc
	Yes 100 kO
— Input resistance (-10 V to +10 V)● -5 V to +5 V	Yes; Physical measuring range: ± 10 V
-5 V to +5 V — Input resistance (-5 V to +5 V)	100 kΩ
Input ranges (rated values), currents	100 K12
• 0 to 20 mA	Yes; Physical measuring range: ± 20 mA
— Input resistance (0 to 20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
• -20 mA to +20 mA	Yes
— Input resistance (-20 mA to +20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
• 4 mA to 20 mA	Yes; Physical measuring range: ± 20 mA
— Input resistance (4 mA to 20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
Input ranges (rated values), resistance thermometer	
• Ni 100	Yes; Standard/climate
— Input resistance (Ni 100)	10 ΜΩ
• Pt 100	Yes; Standard/climate
— Input resistance (Pt 100)	10 ΜΩ
Input ranges (rated values), resistors	
• 0 to 150 ohms	Yes; Physical measuring range: 0 600 ohms
— Input resistance (0 to 150 ohms)	10 ΜΩ
• 0 to 300 ohms	Yes; Physical measuring range: 0 600 ohms
— Input resistance (0 to 300 ohms)	10 ΜΩ
• 0 to 600 ohms	Yes
— Input resistance (0 to 600 ohms)	10 ΜΩ
Cable length	
• shielded, max.	800 m; for U/I, 200 m for R/RTD
Analog outputs	
integrated channels (AO)	2
Voltage output, short-circuit protection	Yes
Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency suppression; for details, see conversion procedure in manual
Output ranges, voltage	
Output ranges, voltage • 0 to 10 V	Yes
	Yes Yes
• 0 to 10 V	
0 to 10 V1 V to 5 V	Yes
0 to 10 V1 V to 5 V-10 V to +10 V	Yes
 0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current	Yes Yes
 0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA 	Yes Yes
 0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 	Yes Yes Yes
 0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA 	Yes Yes Yes
 0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output)	Yes Yes Yes Yes Yes Yes
 0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. 	Yes Yes Yes Yes Yes Yes Yes
0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, inductive load, max. with current outputs, inductive load, max.	Yes Yes Yes Yes Yes $1 \text{ k}\Omega$ 100 nF
 0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. 	Yes Yes Yes Yes Yes $1 \text{ k}\Omega$ 100 nF 500Ω
• 0 to 10 V • 1 V to 5 V • -10 V to +10 V Output ranges, current • 0 to 20 mA • -20 mA to +20 mA • 4 mA to 20 mA Load impedance (in rated range of output) • with voltage outputs, min. • with voltage outputs, capacitive load, max. • with current outputs, inductive load, max. Output • with current outputs, inductive load, max. State length • shielded, max.	Yes Yes Yes Yes Yes $1 \text{ k}\Omega$ 100 nF 500Ω
0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, inductive load, max. with current outputs, inductive load, max. Cable length	Yes Yes Yes Yes Yes Yes $1 \ \text{k}\Omega$ $100 \ \text{nF}$ $500 \ \Omega$ $1 \ \text{mH}$
• 0 to 10 V • 1 V to 5 V • -10 V to +10 V Output ranges, current • 0 to 20 mA • -20 mA to +20 mA • 4 mA to 20 mA Load impedance (in rated range of output) • with voltage outputs, min. • with voltage outputs, capacitive load, max. • with current outputs, inductive load, max. Output • with current outputs, inductive load, max. State length • shielded, max.	Yes Yes Yes Yes Yes Yes $1 \ \text{k}\Omega$ $100 \ \text{nF}$ $500 \ \Omega$ $1 \ \text{mH}$
0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. Cable length shielded, max. Analog value generation for the inputs	Yes Yes Yes Yes Yes Yes $1 \ \text{k}\Omega$ $100 \ \text{nF}$ $500 \ \Omega$ $1 \ \text{mH}$
0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. Cable length shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel	Yes Yes Yes Yes Yes 1 $k\Omega$ 100 nF 500 Ω 1 mH
Oto 10 V 1 V to 5 V 10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. Sale length shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max.	Yes Yes Yes Yes Yes 1 $k\Omega$ 100 nF 500 Ω 1 mH
0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. Cable length shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Interference voltage suppression for interference	Yes Yes Yes Yes Yes Yes $1 \ k\Omega$ $100 \ nF$ $500 \ \Omega$ $1 \ mH$ $200 \ m$ $16 \ bit$ Yes; 2.5 / 16.67 / 20 / 100 ms, acts on all channels
0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. Cable length shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Interference voltage suppression for interference frequency f1 in Hz	Yes Yes Yes Yes Yes Yes $1 \ k\Omega$ $100 \ nF$ $500 \ \Omega$ $1 \ mH$ $200 \ m$ $16 \ bit$ Yes; 2.5 / 16.67 / 20 / 100 ms, acts on all channels
0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. Cable length shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Interference voltage suppression for interference frequency f1 in Hz Smoothing of measured values	Yes Yes Yes Yes
Oto 10 V 1 V to 5 V 10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. with current outputs, inductive load, max. Table length shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Interference voltage suppression for interference frequency f1 in Hz Smoothing of measured values parameterizable	Yes Yes Yes Yes $ 1 \ k\Omega $ $ 100 \ nF $ $ 500 \ \Omega $ $ 1 \ mH $ $ 200 \ m $ $ 16 \ bit $ $ Yes; 2.5 \ / \ 16.67 \ / \ 20 \ / \ 100 \ ms, acts on all channels $ $ 400 \ / \ 60 \ / \ 50 \ / \ 10 $ Yes
 0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. Shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Interference voltage suppression for interference frequency f1 in Hz Smoothing of measured values parameterizable Step: None 	Yes Yes Yes Yes Yes $ 1 \ k\Omega $ $ 100 \ nF $ $ 500 \ \Omega $ $ 1 \ mH $ $ 200 \ m $ $ 16 \ bit $ $ Yes; 2.5 / 16.67 / 20 / 100 \ ms, acts on all channels $ $ 400 / 60 / 50 / 10 $ $ Yes $ $ Yes $
0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, inductive load, max. with current outputs, inductive load, max. Cable length shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Interference voltage suppression for interference frequency f1 in Hz Smoothing of measured values parameterizable Step: None Step: low	Yes Yes Yes Yes Yes $ 1 \ k\Omega $ $ 100 \ nF $ $ 500 \ \Omega $ $ 1 \ mH $ $ 200 \ m $ $ 16 \ bit $ $ Yes; 2.5 \ / \ 16.67 \ / \ 20 \ / \ 100 \ ms, acts on all channels $ $ 400 \ / \ 60 \ / \ 50 \ / \ 10 $ $ Yes $ $ Yes $ $ Yes $ $ Yes $
0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA Load impedance (in rated range of output) with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. Cable length shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Interference voltage suppression for interference frequency f1 in Hz Smoothing of measured values parameterizable Step: None Step: low Step: Medium	Yes Yes Yes Yes Yes Yes $ 1 \ k\Omega $ $ 100 \ nF $ $ 500 \ \Omega $ $ 1 \ mH $ $ 200 \ m $ $ 16 \ bit $ $ Yes; 2.5 \ / \ 16.67 \ / \ 20 \ / \ 100 \ ms, acts on all channels $ $ 400 \ / \ 60 \ / \ 50 \ / \ 10 $ $ Yes $
 0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. Cable length shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Interference voltage suppression for interference frequency f1 in Hz Smoothing of measured values parameterizable Step: None Step: None Step: Medium Step: High 	Yes Yes Yes Yes Yes Yes $ 1 \ k\Omega $ $ 100 \ nF $ $ 500 \ \Omega $ $ 1 \ mH $ $ 200 \ m $ $ 16 \ bit $ $ Yes; 2.5 \ / \ 16.67 \ / \ 20 \ / \ 100 \ ms, acts on all channels $ $ 400 \ / \ 60 \ / \ 50 \ / \ 10 $ $ Yes $
 0 to 10 V 1 V to 5 V -10 V to +10 V Output ranges, current 0 to 20 mA -20 mA to +20 mA 4 mA to 20 mA with voltage outputs, min. with voltage outputs, capacitive load, max. with current outputs, max. with current outputs, inductive load, max. Cable length shielded, max. Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Interference voltage suppression for interference frequency f1 in Hz Smoothing of measured values parameterizable Step: None Step: None Step: Medium Step: High Analog value generation for the outputs 	Yes Yes Yes Yes Yes Yes $ 1 \ k\Omega $ $ 100 \ nF $ $ 500 \ \Omega $ $ 1 \ mH $ $ 200 \ m $ $ 16 \ bit $ $ Yes; 2.5 \ / \ 16.67 \ / \ 20 \ / \ 100 \ ms, acts on all channels $ $ 400 \ / \ 60 \ / \ 50 \ / \ 10 $ $ Yes $

Cattling time	
Settling time	1.5 mg
• for resistive load	1.5 ms 2.5 ms
for capacitive load for inductive load	2.5 ms
	2.5 IIIS
Encoder	
Connection of signal encoders	Vac
for voltage measurement for ourself recoverement as 4 wire transducer	Yes
for current measurement as 4-wire transducer	Yes
 for resistance measurement with two-wire connection 	Yes
 for resistance measurement with three-wire connection 	Yes
for resistance measurement with four-wire connection	Yes
Connectable encoders	
• 2-wire sensor	Yes
permissible quiescent current (2-wire sensor), max.	1.5 mA
Encoder signals, incremental encoder (asymmetrical)	
Input voltage	24 V
 Input frequency, max. 	100 kHz
 Counting frequency, max. 	400 kHz; with quadruple evaluation
Signal filter, parameterizable	Yes
 Incremental encoder with A/B tracks, 90° phase offset 	Yes
 Incremental encoder with A/B tracks, 90° phase offset and zero track 	Yes
• pulse encoder	Yes
pulse encoder pulse encoder with direction	Yes
pulse encoder with one impulse signal per count	Yes
direction	
Errors/accuracies	
Linearity error (relative to input range), (+/-)	0.1 %
Temperature error (relative to input range), (+/-)	0.005 %/K
Crosstalk between the inputs, max.	-60 dB
Repeat accuracy in steady state at 25 °C (relative to input range), (+/-)	0.05 %
Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-)	0.02 %
Linearity error (relative to output range), (+/-)	0.15 %
Temperature error (relative to output range), (+/-)	0.005 %/K
Crosstalk between the outputs, max.	-80 dB
Repeat accuracy in steady state at 25 °C (relative to output range), (+/-)	0.05 %
Operational error limit in overall temperature range	
 Voltage, relative to input range, (+/-) 	0.3 %
• Current, relative to input range, (+/-)	0.3 %
• Resistance, relative to input range, (+/-)	0.3 %
Resistance thermometer, relative to input range, (+/-)	Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K
 Voltage, relative to output range, (+/-) 	0.3 %
Current, relative to output range, (+/-)	0.3 %
Basic error limit (operational limit at 25 °C)	
Voltage, relative to input range, (+/-)	0.2 %
• Current, relative to input range, (+/-)	0.2 %
Resistance, relative to input range, (+/-)	0.2 %
Resistance thermometer, relative to input range, (+/-	Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K,
)	Ni100 Climate: ±0.5 K
 Voltage, relative to output range, (+/-) 	0.2 %
 Current, relative to output range, (+/-) 	0.2 %
Interference voltage suppression for $f = n \times (f1 + /- 1 \%)$, $f1 =$	interference frequency
Interference voltage suppression for f = n x (f1 +/- 1 %), f1 = • Series mode interference (peak value of interference < rated value of input range), min.	interference frequency 30 dB

	40.14
Common mode voltage, max.	10 V
Common mode interference, min.	60 dB; at 400 Hz: 50 dB
Interfaces	
Number of PROFINET interfaces	1
1. Interface	
Interface types	V V4
• RJ 45 (Ethernet)	Yes; X1
Number of ports integrated quiteb	2 Vaa
• integrated switch	Yes
Protocols • IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— Isochronous mode	Yes
 Direct data exchange 	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
 Prioritized startup 	Yes; Max. 32 PROFINET devices
 Number of connectable IO Devices, max. 	128; In total, up to 256 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
Of which IO devices with IRT, max.	64
 Number of connectable IO Devices for RT, max. 	128
— of which in line, max.	128
Number of IO Devices that can be	8; in total across all interfaces
simultaneously activated/deactivated, max.	-,
 Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	, , , , , , , , , , , , , , , , , , , ,
— for send cycle of 250 μs	250 μs to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625 μs of the isochronous OB is decisive
— for send cycle of 500 μs	500 μs to 8 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625 μs of the isochronous OB is decisive
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
 With IRT and parameterization of "odd" send cycles 	Update time = set "odd" send clock (any multiple of 125 $\mu s:$ 375 $\mu s,$ 625 $\mu s \dots 3$ 875 $\mu s)$
Update time for RT	
— for send cycle of 250 μs	250 μs to 128 ms
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services PG/OP communication	Voc
PG/OP communication Isochronous mode	Yes No
— Isocrironous mode — IRT	Yes
— IKT — PROFlenergy	Yes; per user program
— Shared device	Yes
Number of IO Controllers with shared device,	4
max.	

 activation/deactivation of I-devices 	Yes; per user program
Asset management record	Yes; per user program
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
 Autonegotiation 	Yes
 Autocrossing 	Yes
Industrial Ethernet status LED	Yes
Protocols	
Number of connections	
 Number of connections, max. 	96; via integrated interfaces of the CPU and connected CPs / CMs
 Number of connections reserved for ES/HMI/web 	10
 Number of connections via integrated interfaces 	64
Number of S7 routing paths	16
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	
 Media redundancy 	only via 1st interface (X1)
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
 MRP interconnection, supported 	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max.	50
SIMATIC communication	30
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
• S7 routing	Yes
S7 communication, as server	Yes
S7 communication, as server S7 communication, as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	occ offine help (or communication, does data size)
• TCP/IP	Yes
— Data length, max.	64 kbyte
several passive connections per port,	Yes
supported	
ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
UDP multicast	Yes; Max. 5 multicast circuits
• DHCP	Yes
• DNS	Yes
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	V 10 1111
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes
Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
 User authentication 	"anonymous" or by user name & password
 Number of connections, max. 	4
 Number of nodes of the client interfaces, max. 	1 000
 Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/C max. 	300

 Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20
 Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100
Number of simultaneous calls of the client	1
instructions per connection (except OPC_UA_ReadList,OPC_UA_WriteList,OPC_UA_M max.	
 Number of simultaneous calls of the client 	5
instructions OPC_UA_ReadList,OPC_UA_WriteList and OPC_UA_MethodCall, max.	
 Number of registerable nodes, max. 	5 000
 Number of registerable method calls of OPC_UA_MethodCall, max. 	100
 Number of inputs/outputs when calling OPC_UA_MethodCall, max. 	20
OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address space
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
 User authentication 	"anonymous" or by user name & password
 — GDS support (certificate management) 	Yes
Number of sessions, max.	32
Number of accessible variables, max.	50 000
Number of accessible variables, max.	10 000
•	
 Number of subscriptions per session, max. 	20
— Sampling interval, min.	100 ms
— Publishing interval, min.	500 ms
 Number of server methods, max. 	20
 Number of inputs/outputs per server method, max. 	20
 Number of monitored items, max. 	1 000; for 1 s sampling interval and 1 s send interval
 Number of server interfaces, max. 	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
 Number of nodes for user-defined server interfaces, max. 	1 000
 Alarms and Conditions 	Yes
 Number of program alarms 	100
 Number of alarms for system diagnostics 	50
Further protocols	
MODBUS	Yes; MODBUS TCP
Isochronous mode	
	Voc
Equidistance	Yes
S7 message functions	
Number of login stations for message functions, max.	32
Program alarms	Yes
Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	2 500
Number of simultaneously active program alarms	
Number of program alarms	600
 Number of alarms for system diagnostics 	100
 Number of alarms for motion technology objects 	80
Test commissioning functions	
	Voc. Parallal online access pessible for up to E anxinosping quaterns
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	
 Status/control variable 	Yes
 Variables 	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters

 Number of variables, max. 	
of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
Forcing	Yes
 Forcing, variables 	Peripheral inputs/outputs
 Number of variables, max. 	200
Diagnostic buffer	
present	Yes
 Number of entries, max. 	1 000
— of which powerfail-proof	500
Traces	
 Number of configurable Traces 	4; Up to 512 KB of data per trace are possible
nterrupts/diagnostics/status information	
Alarms	
Diagnostic alarm	Yes
Hardware interrupt	Yes
Diagnoses	
Monitoring the supply voltage	Yes
Wire-break	Yes; for analog inputs/outputs, see description in manual
Short-circuit	Yes; for analog outputs, see description in manual
A/B transition error at incremental encoder	Yes
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
STOP ACTIVE LED	Yes
 Monitoring of the supply voltage (PWR-LED) 	Yes
Channel status display	Yes
for channel diagnostics	Yes; For analog inputs/outputs
Connection display LINK TX/RX	Yes
Supported technology objects Motion Control	Yes; Note: The number of technology objects affects the cycle time of
Supported technology objects	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Supported technology objects Motion Control Number of available Motion Control resources for	
Motion Control Number of available Motion Control resources for technology objects	the PLC program; selection guide via the TIA Selection Tool
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	the PLC program; selection guide via the TIA Selection Tool 800
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis	the PLC program; selection guide via the TIA Selection Tool 800
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis	the PLC program; selection guide via the TIA Selection Tool 800 40 80
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value)	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value)	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter ntegrated Functions Counting functions	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter ntegrated Functions Counting functions Counting functions	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter ntegrated Functions Counting functions Counting functions Counter response parameterizable	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes Yes
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter ntegrated Functions Counting functions Counting functions	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes

Event-controlled stop	Yes
Synchronization via digital input	Yes
Counting range, parameterizable	Yes
Comparator	
Number of comparators	2; per count channel; see manual for details
Direction dependency	Yes
— Can be changed from user program	Yes
Position detection	
Incremental acquisition	Yes
 Suitable for S7-1500 Motion Control 	Yes
Measuring functions	
 Measuring time, parameterizable 	Yes
 Dynamic measurement period adjustment 	Yes
 Number of thresholds, parameterizable 	2
Measuring range	
 Frequency measurement, min. 	0.04 Hz
 Frequency measurement, max. 	400 kHz; with quadruple evaluation
 Cycle duration measurement, min. 	2.5 μs
 Cycle duration measurement, max. 	25 s
Accuracy	
 Frequency measurement 	100 ppm; depending on measuring interval and signal evaluation
 Cycle duration measurement 	100 ppm; depending on measuring interval and signal evaluation
Velocity measurement	100 ppm; depending on measuring interval and signal evaluation
Potential separation	
Potential separation digital inputs	
 between the channels 	No
between the channels, in groups of	16
Potential separation digital outputs	
 between the channels 	No
between the channels, in groups of	16
Detential congretion sharpels	
Potential separation channels	
between the channels and backplane bus	Yes
between the channels and backplane busBetween the channels and load voltage L+	Yes No
between the channels and backplane bus	
between the channels and backplane busBetween the channels and load voltage L+	
between the channels and backplane bus Between the channels and load voltage L+ Isolation	No
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with	No
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions	No
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max.	707 V DC (type test) -25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. • vertical installation, min.	707 V DC (type test) -25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max.	707 V DC (type test) -25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation	-25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min.	-25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max.	-25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level	-25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max.	-25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header	-25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header configuration / programming / header	-25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header configuration / programming / header Programming language	-25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header configuration / programming / header Programming language — LAD	-25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header configuration / programming / header Programming language — LAD — FBD	707 V DC (type test) -25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual Yes Yes
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header configuration / programming / header Programming language — LAD — FBD — STL	707 V DC (type test) -25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual Yes Yes Yes
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header configuration / programming / header Programming language — LAD — FBD — STL — SCL	707 V DC (type test) -25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual Yes Yes Yes Yes Yes
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header configuration / programming / header Programming language LAD FBD STL SCL GRAPH	707 V DC (type test) -25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual Yes Yes Yes
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header configuration / programming / header Programming language — LAD — FBD — STL — SCL — GRAPH Know-how protection	707 V DC (type test) -25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual Yes Yes Yes Yes Yes Yes
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header configuration / programming / header Programming language — LAD — FBD — STL — SCL — GRAPH Know-how protection • User program protection/password protection	707 V DC (type test) -25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual Yes Yes Yes Yes Yes Yes
between the channels and backplane bus Between the channels and load voltage L+ Isolation Isolation tested with Ambient conditions Ambient temperature during operation horizontal installation, min. horizontal installation, max. vertical installation, min. vertical installation, max. Ambient temperature during storage/transportation min. max. Altitude during operation relating to sea level Installation altitude above sea level, max. configuration / header configuration / programming / header Programming language — LAD — FBD — STL — SCL — GRAPH Know-how protection	707 V DC (type test) -25 °C; No condensation 60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off -25 °C; No condensation 40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off -40 °C 70 °C 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual Yes Yes Yes Yes Yes

Access protection	
 protection of confidential configuration data 	Yes
 Password for display 	Yes
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
Protection level: Complete protection	Yes
programming / cycle time monitoring / header	
 lower limit 	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	85 mm
Height	147 mm
Depth	129 mm
Weights	
Weight, approx.	1 050 g

last modified: 11/3/2021 **C**